# SRB measures of singular hyperbolic attractors Scuola Normale Superiore di Pisa

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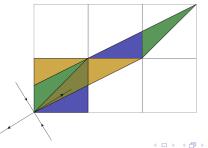
Dominic Veconi (International Centre for The SRB measures of singular hyperbolic attractor

# Hyperbolic sets

- Let M be a Riemannian manifold, U ⊂ M an open set, f : U → M a diffeomorphism onto its image.
- A compact *f*-invariant Λ ⊂ M is a hyperbolic set if there exist constants λ > 1 and c > 0 such that each x ∈ Λ admits a splitting T<sub>x</sub>M = E<sup>s</sup>(x) ⊕ E<sup>u</sup>(x) for which
  - $(df_x)(E^s(x)) = E^s(f(x))$  and  $(df_x)(E^u(x)) = E^u(f(x));$
  - $\|df_x^n(v)\| \leq c\lambda^{-n}\|v\| \ \forall v \in E^s(x);$
  - $\|df_x^{-n}(f)\| \leq c\lambda^{-n}\|v\| \ \forall v \in E^u(x).$
- In this setting, we say f is uniformly hyperbolic on  $\Lambda$ .
- here are foliations  $W^s$  and  $W^u$  of U so that  $T_x W^s(x) = E^s(x)$  and  $T_x W^u(x) = E^u(x)$ , and for which there is a C > 0,  $0 < \alpha < 1$  such that for  $x \in U$ ,
  - $f(W^{s}(x)) = W^{s}(f(x))$  and  $f(W^{u}(x)) = W^{u}(f(x))$ ;
  - $\rho(f^n(x), f^n(y)) \leq C \alpha^n \rho(x, y) \ \forall y \in W^s(x);$
  - $\rho(f^{-n}(x), f^{-n}(y)) \leq C\alpha^n \rho(x, y) \ \forall y \in W^u(x).$
- We call E<sup>s</sup>(x), E<sup>u</sup>(x) the stable/unstable subspaces and W<sup>s</sup>(x), W<sup>u</sup>(x) the stable/unstable submanifolds at x ∈ U.

## Example: Anosov diffeomorphisms

- If Λ = M is a hyperbolic set for f, then f is an Anosov diffeomorphism.
- Consider the linear automorphism  $A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \in SL(2, \mathbb{Z})$ . Let  $f : \mathbb{T}^2 \to \mathbb{T}^2$  be the induced map on  $\mathbb{T}^2 = \mathbb{R}^2 / \mathbb{Z}^2$ .
- A has two eigendirections corresponding to the eigenvalues  $\lambda^{-1} < 1 < \lambda$ . These affine eigenspaces at each point in  $\mathbb{R}^2$  descend to stable/unstable manifolds in  $\mathbb{T}^2$ .

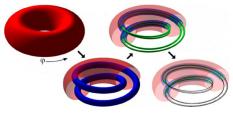


## Example: Smale-Williams Solenoid

• Consider a map  $F:\mathbb{S}^1 imes\mathbb{D} o\mathbb{S}^1 imes\mathbb{D}$  of the solid torus given by

$$F(\varphi, x, y) = \left(2\varphi, \frac{1}{2}\cos(\varphi) + \frac{1}{5}x, \frac{1}{2}\sin(\varphi) + \frac{1}{5}y
ight)$$

 Near the direction of S<sup>1</sup>, this map is expanding; in the direction of D, the map is contracting.



Notice: The toral automorphism f : T<sup>2</sup> → T<sup>2</sup> preserved Lebesgue area. The solenoid map F : S<sup>1</sup> × D → S<sup>1</sup> × D does not preserve volume; in fact, the solenoid map is *dissipative* with respect to volume.

# Singular hyperbolic attractors

#### Setting:

- M Riemannian manifold, K ⊂ M open and precompact, N ⊂ K closed, N<sup>+</sup> = N ∪ ∂K;
- $f: K \setminus N \to K$  diffeomorphism onto its image;
- N<sup>−</sup> = image of continuous extensions of f to N<sup>+</sup> ⊂ K
  ; or more formally,

$$N^- = \left\{ y \in K : \exists z \in N^+, z_n \in K \setminus N \text{ s.t. } z_n \rightarrow z, f(z_n) \rightarrow y 
ight\}$$

• 
$$K^+ = \{x \in K : f^n(x) \notin N^+ \ \forall n \ge 0\};$$

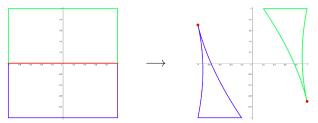
- $D = \bigcap_{n \ge 0} f^n(K^+)$ ,  $\Lambda = \overline{D}$  ( $\Lambda$  is the *attractor* for f).
- Λ is a singular hyperbolic attractor if there is a continuous splitting z → E<sup>s</sup>(z) ⊕ E<sup>u</sup>(z) over K \ N into stable and unstable subspaces. In particular, there are C > 0 and λ > 1 so that for any z ∈ D, n ≥ 0:

$$\begin{aligned} \|df_z^n v\| &\leq C\lambda^{-n} \|v\| \quad \forall v \in E^s(z); \\ \|df_z^{-n} v\| &\leq C\lambda^{-n} \|v\| \quad \forall v \in E^u(z). \end{aligned}$$

#### Example 1: Geometric Lorenz attractor

• 
$$I = (-1, 1), K = I \times I, N = I \times \{0\}, f : K \setminus N \to K$$
 given by  
 $f(x, y) = (\varphi(x, y), \psi(x, y)),$  where  
 $\varphi(x, y) = (\operatorname{sgn}(y)Bx|y|^{\nu} - B|y|^{\nu_0} + 1)\operatorname{sgn}(y)$   
 $\psi(x, y) = ((1 + A)|y|^{\nu_0} - A)\operatorname{sgn}(y)$ 

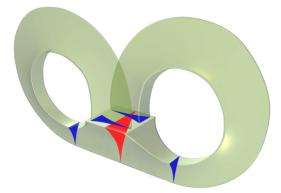
where 0 < A < 1,  $0 < B < \frac{1}{2}$ ,  $\nu > 1$ , and  $1/(1 + A) < \nu_0 < 1$ .



• The two dots form the set  $N^-$ , the "image" of the singular set N.

#### Example: Geometric Lorenz attractor

The geometric Lorenz attractor is a Poincaré first-return map for a transverse cross-section of the flow of the classical Lorenz attractor.



#### Example: Lorenz-type maps

More generally, a *Lorenz-type map* is a map  $f : K \setminus N \to K$ ,  $K = I \times I$ ,  $N = I \times \{a_0, a_1, \dots, a_{q+1}\}$ , where

$$-1 = a_0 < a_1 < \cdots < a_q < a_{q+1} = 1$$

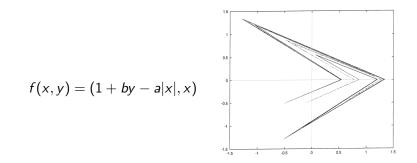
and, in addition to certain regularity conditions on df,

- $\lim_{y\uparrow a_i} f(x,y) = f_i^-$ ,  $\lim_{y\downarrow a_i} f(x,y) = f_i^+$  ( $f_i^\pm \in \overline{K \setminus N}$  constant points, independent of  $x \in I$ );
- $f|_{I \times (a_i, a_{i+1})} : I \times (a_i, a_{i+1}) \to K$  is a diffeomorphism onto its image;
- $\|\varphi_x\|, \|\psi_y^{-1}\| < 1$ , where  $f(x, y) = (\varphi(x, y), \psi(x, y))$ .

#### Theorem (Afraimovich, Bykov, Shilnikov '83)

If M is a compact Riemannian manifold  $w/\dim M \ge 3$ , there exists a vector field X and a smooth submanifold S such that the first-return time map f induced on S by the flow given by X is a Lorenz-type map.

Lozi map: A simplified Hénon map f : K \ N → K, K = (-c, c)<sup>2</sup>, c ∈ (0, 1.5), N = {0} × (-c, c), a > 0, b > 0 sufficiently small:



• In this case, the map is continuous on N, but not differentiable.

## SRB measures

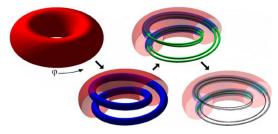
- Suppose f : U → M is a hyperbolic map on a Riemannian manifold M. An SRB measure is an invariant Borel probability measure μ for which:
  - f has positive Lyapunov exponents  $\mu$ -a.e., and
  - μ admits absolutely continuous conditional measures on the unstable leaves W<sup>u</sup>(x) (w.r.t. Riemannian leaf volume)
- SRB measures are hyperbolic *physical measures*: m(B<sub>μ</sub>) > 0, where m is the Lebesgue/Riemannian volume and B<sub>μ</sub> is the *basin* of μ:

$$\mathcal{B}_{\mu} := \left\{ x : \frac{1}{n} \sum_{k=0}^{n-1} \left( \varphi \circ f^{k} \right) (x) \xrightarrow{n \to \infty} \int_{U} \varphi \, d\mu \quad \forall \varphi \in C^{0} \right\}$$

• In ergodic theory, invariant measures correspond to stationary distributions in probability theory. So SRB measures are *stationary distributions that satisfy the strong law of large numbers on a set of positive volume.* 

### Conservative and dissipative systems

- If f : M → M is an area-preserving diffeomorphism (e.g. Anosov map), then the Lebesgue/Riemannian volume is an SRB measure.
- What if *f* is dissipative? Recall the solenoid map:



- The attractor Ω = ∩<sub>n≥1</sub> F<sup>n</sup>(S<sup>1</sup> × D) is locally a product of an interval and a Cantor set. In particular, it has Lebesgue measure 0.
- The SRB measure is a product of normalized Lebesgue measure on  $\mathbb{S}^1 = \mathbb{R}/2\pi\mathbb{R}$  and the Bernoulli measure on the Cantor set.

#### Theorem (Sinai '72, Bowen, Ruelle '75, Ruelle '76)

Suppose  $f : U \to M$  is  $C^{1+\alpha}$  and  $\Lambda = \bigcap_{n\geq 0} f^n(U)$  is uniformly hyperbolic. Then there are at most finitely many ergodic SRB measures on  $\Lambda$ . If, furthermore,  $f|_{\Lambda}$  is topologically transitive, then there is a unique SRB measure  $\mu$  on  $\Lambda$ , and  $\mathcal{B}_{\mu}$  has full measure in U.

#### Theorem (Rodriguez-Hertz, Rodriguez-Hertz, Tahzibi, Ures '10)

If  $f: M \to M$  is a topologically transitive  $C^{1+\alpha}$  diffeomorphism, then it admits at most one SRB measure.

#### Theorem (Pesin '92)

Suppose  $f : K \setminus N \to K$  admits a singular hyperbolic attractor  $\Lambda$ . Then there are at most countably many ergodic SRB measures supported on  $\Lambda$ .

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#### Stable and unstable manifolds

- We use *unstable manifolds* to construct SRB measures.
- Assume f : K \ N → K is singular hyperbolic with attractor Λ, and let ρ denote the Riemannian distance in M ⊃ K, m the Riemannian measure.

#### Theorem (Pesin '92)

For m-a.e. every  $z \in K \setminus N$ , there are embedded submanifolds  $W_{loc}^{s}(z)$ and  $W_{loc}^{u}(z)$  containing z for which  $T_{z}W_{loc}^{s}(z) = E^{s}(z)$  and  $T_{z}W_{loc}^{u}(z) = E^{u}(z)$ . Furthermore, there is an  $\alpha < 1$  and C > 0 for which, for all  $n \geq 0$ , letting  $\rho$  denote Riemannian distance,

$$\begin{split} \rho(f^n(x), f^n(y)) &\leq C\alpha^n \rho(x, y) \quad for \; x, y \in W^s_{\text{loc}}(z), \\ \rho(f^{-n}, f^{-n}(y)) &\leq C\alpha^n \rho(x, y) \quad for \; x, y \in W^u_{\text{loc}}(z). \end{split}$$

Additionally, for  $w \in N \setminus K$  sufficiently close to z, the intersection  $W_{loc}^{s}(z) \cap W_{loc}^{u}(w)$  is nonempty and contains exactly one point.

- Define W<sup>u</sup>(z) = ∪<sub>n≥0</sub> f<sup>n</sup> (W<sup>u</sup><sub>loc</sub>(f<sup>-n</sup>(z))) for z ∈ K (W<sup>s</sup>(z) is defined analogously for z ∈ Λ).
- Let J<sup>u</sup>(z) = det (df|<sub>E<sup>u</sup>(z)</sub>) denote the unstable Jacobian of f at a point z ∈ Λ. For y ∈ W<sup>u</sup>(z), set

$$\kappa(z,y) = \prod_{j=0}^{\infty} \frac{J^{u}\left(f^{-j}(z)\right)}{J^{u}\left(f^{-j}(y)\right)}$$

• Let  $m_z^u$  and  $\rho_z^u$  be the Riemannian leaf volume and leaf metric on  $W^u(z)$ . Let  $U_0 := B^u(z, r) \subset W^u_{\text{loc}}(z)$  be the disc of  $\rho_z^u$ -radius r centered at z.

• Finally let 
$$U_n = f(U_{n-1}) \setminus N^+$$
.

## Construction of SRB measures (cont.)

• Define the measures  $\widetilde{\nu}_n$  on  $U_n \subset W^u(f^n(z))$  by

$$d\widetilde{\nu}_n(y) = \widetilde{C}_n(z)\kappa(f^n(z), y)dm_z^u(y),$$

where  $\widetilde{C}_n(z)$  is a normalizing factor.

- Let  $\nu_n$  be the measure on  $\Lambda$  given by  $\nu_n(A) = \tilde{\nu}_n(A \cap U_n)$  for Borel  $A \subset \Lambda$ .
- Each ν<sub>n</sub> is defined only on subsets of a particular unstable manifold W<sup>u</sup>(f<sup>n</sup>(z)).
- Define:

$$\mu_n = \frac{1}{n} \sum_{k=0}^{n-1} \nu_k$$

• The final step in the construction is to show  $\mu_n$  has an *f*-invariant weak limit measure  $\mu$  concentrated on *D*. (Note  $\mu$  may depend on the reference point *z*.)

#### Setting:

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- $f: K \setminus N \to K$  diffeomorphism onto its image;
- N<sup>−</sup> = image of continuous extensions of f to N<sup>+</sup> ⊂ K; or more formally,

$$N^- = \left\{ y \in K : \exists z \in N^+, z_n \in K \setminus N \text{ s.t. } z_n \to z, f(z_n) \to y \right\}$$

(for example,  $N^- = \{f_i^{\pm} : 1 \le i \le q\}$  for Lorenz-type maps, where  $f_i^+ = \lim_{y \downarrow a_i} f(x, y)$  and  $f_i^- = \lim_{y \uparrow a_i} f(x, y)$ );

• A a singular hyperbolic attractor, expansive constant  $\lambda > 1$ .

Assumptions:

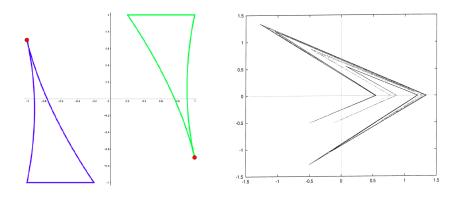
- *N* is a disjoint union of finitely many closed submanifolds  $N_1, \ldots, N_m$  with boundary, of dimension equal to the codimension of  $W^u$ ;
- **②** The local unstable manifolds  $W_{loc}^u(x)$  intersect the singular set N transversally, with angle uniformly bounded away from 0;
- $\ \, { o } \ \, f^j(N^-) \cap N = \varnothing \ \, { for } \ 0 \leq j < k, \ \lambda^k > 2.$

#### Theorem (V. 2022)

If  $f : K \setminus N \to K$  as above satisfies these assumptions, then the attractor  $\Lambda$  admits finitely many ergodic SRB measures.

#### Lorenz and Lozi revisited

 This implies, in particular, that the attractors for both Lorenz-type maps and the Lozi map admit finitely many SRB measures. (Observe that W<sup>u</sup><sub>loc</sub>(x) lies inside the attractor Λ for all x ∈ Λ where W<sup>u</sup><sub>loc</sub>(x) is defined.)



- Assumption that N is a finite union of submanifolds is required for arguments. Result may not hold if N has infinitely many components.
- Example: Take a countable number of horizontal lines in  $(-1,1)^2$ .
- In each resulting section, embed a copy of the geometric Lorenz attractor.
- Each section admits its own SRB measure.
- The proof of the main result requires a lower bound on the distance between components of *N*, which we don't have in this example.

- Is there a connection between the number/supports of SRB measures and the topological properties of the dynamics (e.g. topological transitivity/transitive components)?
- Given  $z \in K \setminus N$ , there is a radius r = r(z) > 0 for which  $W^s_{\text{loc}}(z) \cap B_r(z)$  is the graph of a  $C^1$  function  $\psi_z : U_z \to M$ ,  $U_x z \subset T_z W^s_{\text{loc}}(z)$ .
- W<sup>s</sup> is locally continuous if y → ψ<sub>y</sub> and (y, u) → d(ψ<sub>y</sub>)<sub>u</sub> are continuous over y ∈ (K \ N) ∩ B<sub>r(x)</sub>(x), u ∈ U<sub>y</sub> ⊂ T<sub>y</sub>W<sup>s</sup>(y). (Note ψ<sub>y</sub> is defined μ-a.e. in (K \ N) ∩ B<sub>r(x)</sub>(x), μ any SRB measure.)
- In particular, the maximal radius  $z \mapsto r(z)$  in which  $W^s_{\text{loc}}(z) \cap B_{r(z)}(z)$  is a  $C^1$  curve varies continuously over  $\Lambda$ .

#### Theorem (Pesin 1992, V. 2022)

Let  $f : K \setminus N \to K$  be singular hyperbolic.

- There is a countable collection of f-invariant subsets {U<sub>i</sub>}<sub>i≥1</sub>, open in Λ, for which U<sub>i≥1</sub> U<sub>i</sub> = Λ, and each of which is supported by exactly one ergodic SRB measure.
- If N is a finite disjoint union of embedded submanifolds of dimension equal to the codimension of W<sup>u</sup>, and if each unstable curve W<sup>u</sup> intersects N transversally with angle uniformly bounded away from 0, then this collection is finite.
- If f |<sub>∧</sub> : ∧ → ∧ is topologically transitive, then U<sub>1</sub> = ∧ is the only member of this collection, and thus the ergodic SRB measure is unique.

## Construction of ergodic components

- The construction of the ergodic components  $U_i$  is due to Pesin '92.
- Let  $\mu$  be an SRB measure for  $\Lambda$ . For  $\mu$ -a.e.  $z \in \Lambda$ ,  $W^u_{loc}(z) \subset \Lambda$  and the stable discs  $B^s_{r(y)}(y)$  are defined for  $m^u_z$ -a.e.  $y \in W^u_{loc}(z)$ , i.e. on a set  $A^u(z) \subset W^u_{loc}(z)$  of full  $m^u_z$ -measure. (Recall  $m^u_z$  is the Riemannian leaf volume of  $W^u_{loc}(z)$ .)
- Define the set

$$Q(z) = \left(\bigcup_{y \in A^u(z)} B^s_{r(y)}(y)\right) \cap \Lambda \cap B_{r(z)}(z).$$

Note  $\mu(Q(z)) > 0$ .

- Note Q = U<sub>n∈ℤ</sub> f<sup>n</sup>(Q(z)) is f-invariant, and thus an ergodic component of μ.
- Openness of Q (mod 0) in ∧ follows from the local continuity of W<sup>s</sup> (i.e. continuity of y → r(y) for y ∈ W<sup>u</sup><sub>loc</sub>(z)).

## Proof of finiteness: Preliminary constructions

- Recall  $K^+ = \{x \in K : f^n(x) \notin N^+ \ \forall n \ge 0\}$  and  $D = \bigcap_{n \ge 0} f^n(K^+)$ .
- Given  $\delta > 0$ , let  $B_{\delta}^{-} \subset D$  consist of those  $x \in D$  for which  $W_{\delta}^{u}(y)$  exists and contains x, for some  $y \in D$ .
- Suppose  $\delta_1 < \delta_2$ . Then  $B^-_{\delta_2} \subseteq B^-_{\delta_1}$ .
  - Indeed, if  $x \in B_{\delta_2}^-$ , then  $x \in W_{\delta_2}^u(y)$  for some  $y \in D$ .
  - By certain regularity hypotheses, D ∩ W<sup>u</sup><sub>δ2</sub>(y) has full measure, so can pick y' ∈ W<sup>u</sup><sub>δ2</sub>(y) that is with δ<sub>1</sub>-distance to x.
  - Follows that  $x \in B_{\delta_1}^-$ .

#### Lemma

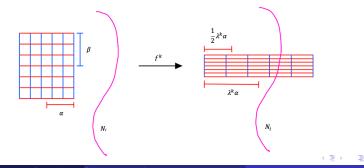
# There exists a $\delta_0 > 0$ so that if $\mu$ is an ergodic SRB measure of $f : \Lambda \to \Lambda$ , $\mu(B_{\delta_0}^-) > 0$ .

# Proving first lemma

- B<sup>-</sup><sub>δ</sub> is the set of points whose local unstable leaves have radius δ > 0.
- Recall  $N = \bigcup_{i=1}^{m} N_i$ , and if U is a neighborhood of N, then f(U) is a neighborhood of  $N^-$ .
- Since f<sup>j</sup>(N<sup>-</sup>) ∩ N = Ø for 1 ≤ j < k, λ<sup>k</sup> > 2 (λ > 1 expansive constant), and N and f<sup>k</sup>(N<sup>-</sup>) are closed, there is a radius Q > 0 so that:
  - the open neighborhoods  $B_Q(N_i)$ ,  $1 \le i \le m$ , are disjoint;
  - $f^j(B_Q(N_i)) \cap N = \emptyset$  for  $1 \le j < k$ .
- We let  $\delta_0 < Q$ .
- Choose ergodic SRB measure μ, and μ-generic point x ∈ D. Using hyperbolic product structure, construct rectangle R of stable leaves of radius β > 0 and unstable leaves of radius α > 0. Then μ(R) > 0.
- f(R) is a rectangle whose unstable leaves have length  $\lambda \alpha$ .

# Proving first lemma (cont)

- Idea: Use iterates of R to extend the unstable leaves until they are of radius  $\geq \delta_0$ . Once this happens,  $f^j(R) \subset B^-_{\delta_0}$ , and  $\mu(B^-_{\delta_0}) > \mu(f^j(R)) = \mu(R) > 0$ .
- Obstruction: What if f<sup>j</sup>(R) ∩ N ≠ Ø before λ<sup>j</sup>α > δ<sub>0</sub>?
- Since δ<sub>0</sub> > Q, Q = radius of disjoint neighborhoods of components of N, f<sup>j</sup>(R) lies in one of these neighborhoods.
- Choose new rectangle  $R_1$  of radius  $\alpha_1 \geq \frac{1}{2}\lambda^j \alpha$ .



# Proving first lemma (cont)

- Iterate R<sub>1</sub> until either:
  - $\lambda^{j} \alpha_{1} \geq \delta_{0}$  (in which case  $\mu(B_{\delta_{0}}^{-}) > 0$ , and we're done); or
  - $f^{j_1}(R_1) \cap N \neq \emptyset$  for some  $j_1 \ge k$  (since  $R_1 \subset B_Q(N_i)$ ).
- In latter case, take new rectangle  $R_2 \subset f^{j_1}(R_1) \setminus N$  with unstable leaves of radius  $\alpha_2 \geq \frac{1}{2} \lambda^{j_1} \alpha_1$ .
- Repeat this process. Each time a rectangle intersects N, we take a leaf of at least half the radius, creating a sequence of rectangles  $\{R_{\ell}\}$  with unstable leaves of radii

$$\alpha_{\ell} \geq \frac{1}{2^{\ell}} \lambda^{j_1 + \dots + j_{\ell}} \alpha_1 > \frac{\lambda^{k\ell}}{2^{\ell}} \alpha_1 = \left(\frac{\lambda^k}{2}\right)^{\ell} \alpha_1,$$

with each  $j_{\ell} \ge k$  the time it takes for  $R_{\ell}$  to intersect N.

• Since  $\lambda^k > 2$ , this will eventually exceed  $\delta_0$ , at which point  $0 < \mu(R_\ell) \le \mu(B_{\delta_0}^-)$ .

# Proving finiteness

- The main result is proven once we show  $B^-_{\delta_0}$  is charged by at most finitely many ergodic SRB measures
- Let  $\Lambda^0 \subset \Lambda$  be the points on which the limits

$$\varphi_{\pm}(x) = \lim_{n \to \infty} \frac{1}{n} \sum_{k=0}^{n-1} \varphi|_{\Lambda} \left( f^{\pm k}(x) \right)$$

both exist for every  $\varphi \in C^0(K)$ . Then  $\mu(\Lambda^0) = 1$  by Birkhoff ergodic theorem, w.r.t. any invariant  $\mu$ .

- Partition  $\Lambda^0$  into equivalence classes on which  $\varphi_+$  and  $\varphi_-$  are constant (and equal).
- These equivalence classes are clopen in Λ. Since Λ is compact, there are at most finitely many equivalence classes.
- Any ergodic SRB measure on Λ is supported on one of these equivalence classes, and each equivalence class can support at most one SRB measure.

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